

Bargaining Games

12-1

So far we have analyzed only non-cooperative games, where agents cannot communicate with each other. However, we have seen situations where taking decisions collectively may be better. Recall: the ideas of correlated equilibria in games, where strategies are defined over an action profile, rather than on individual actions.

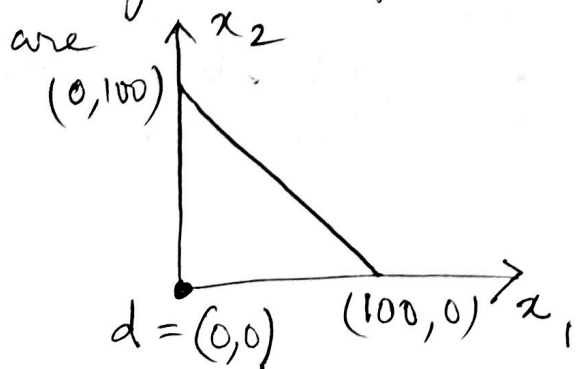
- The model of game theory, that deals with agents collectively, is called "cooperative games".
- Note: this model only opens up the option of communicating with each other. The agent still remain self-interested, i.e., they still want to maximize their own reward.

The first model to consider in cooperative games is the "bargaining" model.

Setting: A set of possible outcomes are bargained on, and finally ~~on~~ certain outcomes are recommended to the players by an arbitrator (trusted ~~agent~~ third party)

Example: 2 players divide $\text{₹}100$ among them.

If their bargain is successful, they divide the money accordingly, otherwise, none gets anything. The failure to reach an agreement is denoted as a disagreement point, $d = (0, 0)$. The possible allocations



If the value of money for each agent is equal to the money itself

Then the set

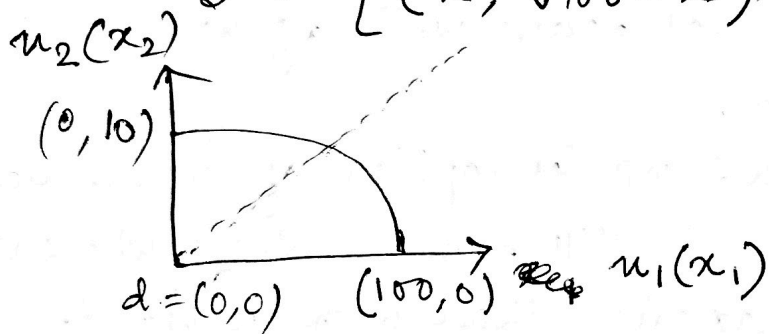
$$S = \{(x, 100 - x) : 0 \leq x \leq 100\}$$

denotes the utility space of all possible allocations.

12-2
It is also reasonable to assume that the money be equally split among them.

Suppose agent 1's value for money is $u_1(x) = x$ and agent 2's: $u_2(x) = \sqrt{x}$. Then the utility space for all allocations

$$\hat{S} = \left\{ (x, \sqrt{100-x}) : 0 \leq x \leq 100 \right\}$$



In this case a reasonable division would lead to equal utility and not equal money.

Model: Bargaining between two agents using a set $S \subseteq \mathbb{R}^2$ - set of feasible allocations and a vector $d \in \mathbb{R}^2$ - disagreement point.

A bargaining problem instance is the tuple (S, d) . A solution concept should find a point in S that satisfies a set of desirable properties - axiomatic approach.

Notation for vectors, say $x, y \in \mathbb{R}^n$
 $x \succeq y \Rightarrow x_i \succeq y_i \forall i, x_j > y_j$ for some j .
 $x \succ y \Rightarrow x_i > y_i \forall i$.

$x \cdot y = (x_i y_i, i \in \{1, \dots, n\})$ elementwise product.

Bargaining game [some additional details]

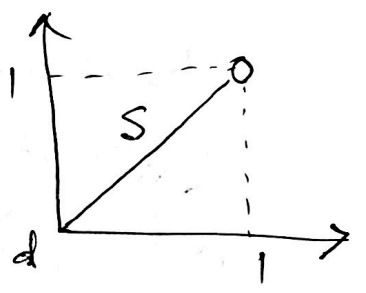
- is an ordered pair (S, d) , $S \subset \mathbb{R}^2$, $d \in \mathbb{R}^2$
- S is a nonempty, compact, and convex set - the set of alternatives.
- $d = (d_1, d_2)$ is the disagreement point.
- \exists ~~at least~~ $x = (x_1, x_2) \in S$ satisfying $x \gg d$.

Collection of all bargaining games ~~is~~ is denoted by \mathcal{G} .

Why these assumptions on the set S ?

Compact = closed + bounded in \mathbb{R}^m

- closed: s.t. all sequences have a limit point within the set. In the example, each point has a better point in the set S , but the limit of that sequence is not in S . $S = \{(x, x) : 0 \leq x < 1\}$



- bounded: ~~own~~ objective / players' objectives are to maximize their payoffs from this set. But that maximal ~~point~~ _{value} needs to be bounded.

- convex: weighted average of possible alternatives is also an alternative. e.g., a lottery that chooses one possible outcome w.p. p and another w.p. $(1-p)$ should be possible to achieve via the bargaining process.

- $\exists x \in S$, s.t. $x \gg d$: to avoid degenerate solutions.

Solution concept in bargaining game:

$$\phi : \mathcal{G} \rightarrow \mathbb{R}^2 \text{ s.t. } \phi(S, d) \in S \text{ for each game } (S, d) \in \mathcal{G}$$

~~set of all bargaining games~~

Desirable properties

① Symmetry: (S, d)

A bargaining game is symmetric if

(a) $d_1 = d_2$

(b) if $x = (x_1, x_2) \in S$, then $(x_2, x_1) \in S$

Defn:

A solution concept ϕ is symmetric if for every symmetric bargaining

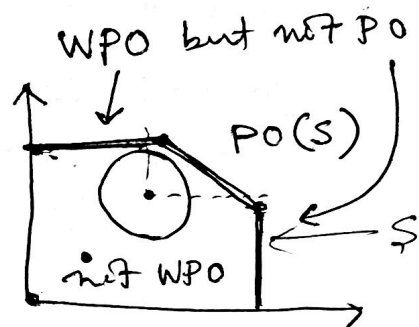
game (S, d) , $\phi(S, d)$ is s.t. $\phi_1(S, d) = \phi_2(S, d)$



② Efficiency:

An alternative $x \in S$ is an efficient point if $\nexists y \in S, y \neq x$ s.t. $y \succcurlyeq x$ [all agents weakly

prefer y to x and at least one agent strictly]



→ An alternative $z \in S$ is weakly efficient

if $\nexists y \in S, y \neq z$ s.t. $y \gg z$.

[all agents strictly prefer y to z]

$PO(S)$: set of all Pareto optimal (efficient) points

Defn: A solution concept ϕ is efficient if

$\phi(S, d) \in PO(S)$ for every bargaining game $(S, d) \in \mathcal{G}$.

③ Covariance under positive affine transformation

motivation: the bargaining solution should be scale-free - independent of the units of utility also, should be affected in the same way a translation is introduced to the possible allocations.

$$aS + b = \{(as + b) : s \in S\}$$

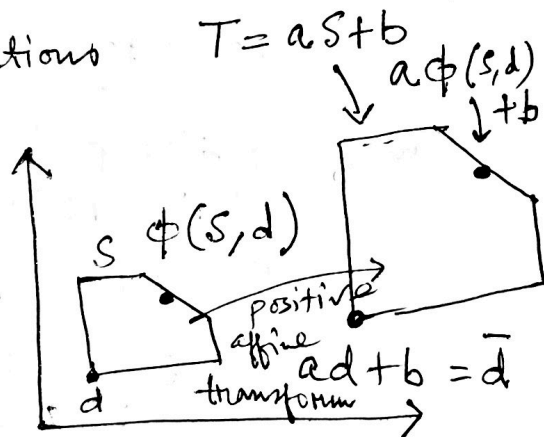
$$= \{(a_1s_1 + b_1, a_2s_2 + b_2) : (s_1, s_2) \in S\}$$

similarly $ad + b = (a_1d_1 + b_1, a_2d_2 + b_2)$

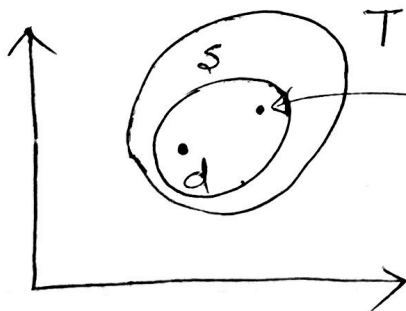
Defn: A solution concept ϕ is covariant under positive affine transformations if for every bargaining game $(S, d) \in \mathcal{F}$, for every $a \in \mathbb{R}^2, a \gg 0$, and $b \in \mathbb{R}^2$

$$\phi(aS + b, ad + b) = a\phi(S, d) + b$$

↑ transform set of feasible allocations and disagreement points



④ Independence of Irrelevant Alternatives



$$S \subseteq T$$

$$\phi(T, d)$$

What should $\phi(S, d)$ be?

Will be strange if $\phi(S, d)$ is not the same, since that option was available in T .

Defn: A solution concept ϕ satisfies IIA if for every bargaining game $(T, d) \in \mathcal{F}$ and for every $S \subseteq T$

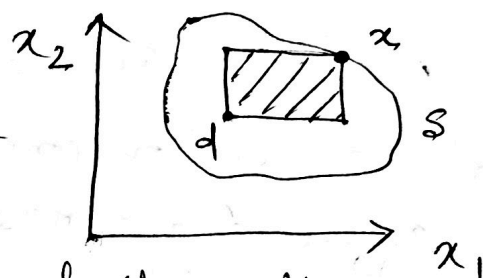
$$\phi(T, d) \in S \Rightarrow \phi(S, d) = \phi(T, d)$$

The Nash solution

Thm! There exists a unique solution concept N for the family of bargaining games \mathcal{F} satisfying symmetry, efficiency, IIA, covariance under positive affine transformations.

$$N(S, d) = \operatorname{argmax}_{x \in S, x \geq d} (x_1 - d_1)(x_2 - d_2)$$

— The x that maximizes the area of the rectangle with axis-parallel



~~the~~ left-bottom corner as d and stays within S .

Recall, S is convex, compact, and has at least one "better" point than d .

Proof in three parts:

- the $N(S, d)$ point is unique
- $N(S, d)$ satisfies the four properties
- Any solution concept that satisfied the four properties must be identical to $N(S, d)$

Lemma 1! For every bargaining game ~~there is~~ (S, d) , there exists a unique point in the set $N(S, d)$.

Proof: Suppose not, then we show we can construct a point that improves the Nash product, contradiction.

First, do a coordinate transformation by adding $-d$ to all points in (S, d) , i.e., the new game is $(S-d, (0, 0))$

The Nash product is therefore

$$\operatorname{argmax}_{\{z \in S-d, z \succ 0\}} z_1 z_2$$

Note: The value of the product is unchanged due to the coordinate transform. Let $f(z) = z_1 z_2$.

This is a continuous function and the domain on which it is maximized, $D := \{z \in S-d, z \succ 0\}$ is compact, and convex. Also $D \neq \emptyset$ by assumption of S .

Hence, a maxima is guaranteed to exist.

Suppose, it is not unique i.e.

$$c^* = y_1 y_2 = v_1 v_2$$

both gives rise to the same maximum value of the product.

consider a new point

$$w = \frac{1}{2} y + \frac{1}{2} v$$

$w \in D$, because of convexity

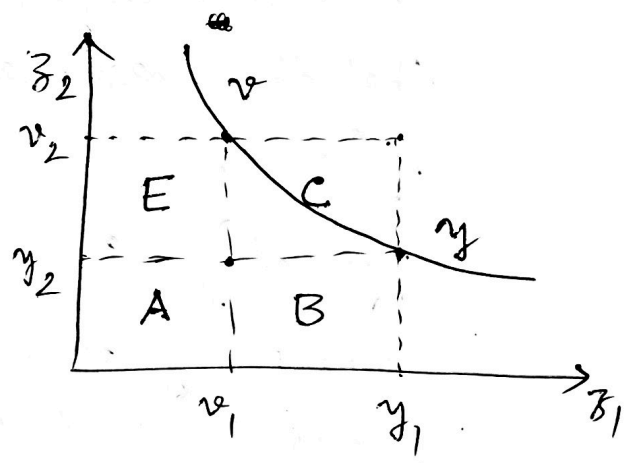
$$\text{Then } w_1 w_2 = \left(\frac{1}{2} y_1 + \frac{1}{2} v_1\right) \left(\frac{1}{2} y_2 + \frac{1}{2} v_2\right)$$

$$= \frac{1}{4} y_1 y_2 + \frac{1}{4} v_1 v_2 + \frac{1}{4} (y_1 v_2 + v_1 y_2)$$

$$\left[\begin{aligned} y_1 v_2 + v_1 y_2 &= A + B + C + E + A = 2A + B + C + E \\ y_1 y_2 + v_1 v_2 &= A + E + A + B = 2A + B + E \end{aligned} \right]$$

$$> \frac{1}{4} (y_1 y_2 + v_1 v_2) + \frac{1}{4} (y_1 y_2 + v_1 v_2)$$

$$= c^* \quad \rightarrow \leftarrow$$



Lemma 2: $N(S, d)$ satisfies symmetry, efficiency, covariance under positive affine transformations, and 11A.

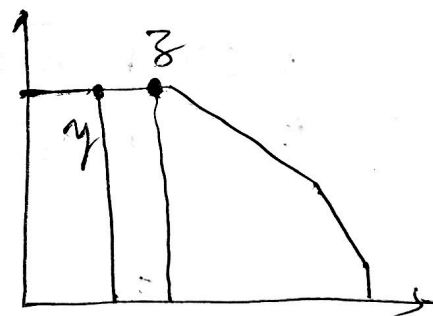
Proof: (Symmetry) ~~Suppose~~ given $d_1 = d_2 = d$ and S is symmetric. Suppose y^* maximizes

$$(y_1 - d)(y_2 - d)$$

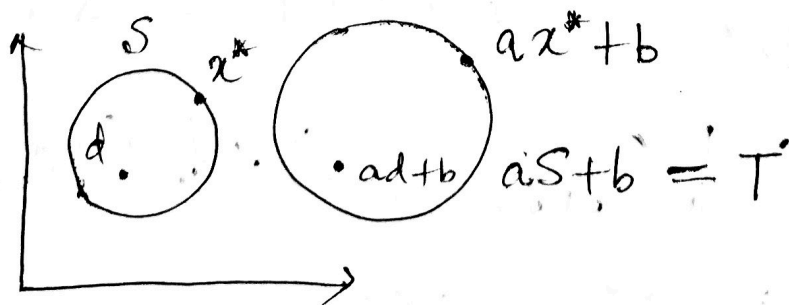
Then $y^* = (y_1^*, y_2^*)$ and $z = (y_2^*, y_1^*) \in S$ also maximizes the product. Since we know that the maxima has to be unique, then $y_1^* = y_2^*$.

(efficient) Suppose not, if z is s.t. $z \succ y$ where y is the optimal argument for the Nash product. But then $(z_1 - d_1)(z_2 - d_2)$ strictly improves the area of the rectangle/Nash product.

Contradicts that y is Nash optimal.



(~~CO~~CPAT) Suppose $x^* = N(S, d)$ is the Nash optimal solution. Consider $aS + b$, where $a >> 0$.



translation b does not change the area of a rectangle.

modified objective function

12-9.

$$\begin{aligned} \operatorname{argmax}_{s_1, s_2} & ((a_1 s_1 + b_1) - (a_1 d_1 + b_1)) ((a_2 s_2 + b_2) - (a_2 d_2 + b_2)) \\ &= \operatorname{argmax}_{s_1, s_2} a_1 a_2 (s_1 - d_1)(s_2 - d_2) = x^* \end{aligned}$$

Hence, the optimal solution in T is $a x^* + b$.

(IIA) Straightforward since if a maxima of a function over a larger set stays in a smaller set, that continues to be the optimal even in the smaller set.

Lemma 3: Every solution concept ϕ satisfying symmetry, efficiency, CPAT, and IIA is identical to N .

Proof idea: Use PAT to move d to $(0,0)$ and the ~~optimal~~ Nash optimal point $y^* = N(S, d)$ to $(1,1)$.
- Use the 4 properties to show that $\phi(S, d)$ that satisfies these 4 must be y^* .

Step 1: Since \exists at least one $x \in S$ s.t. $x \gg d$

$$y^* \gg d$$

$$L(x_1, x_2) = \left(\frac{x_1 - d_1}{y_1^* - d_1}, \frac{x_2 - d_2}{y_2^* - d_2} \right), x \in S.$$

$$\text{clearly } L(d_1, d_2) = (0, 0)$$

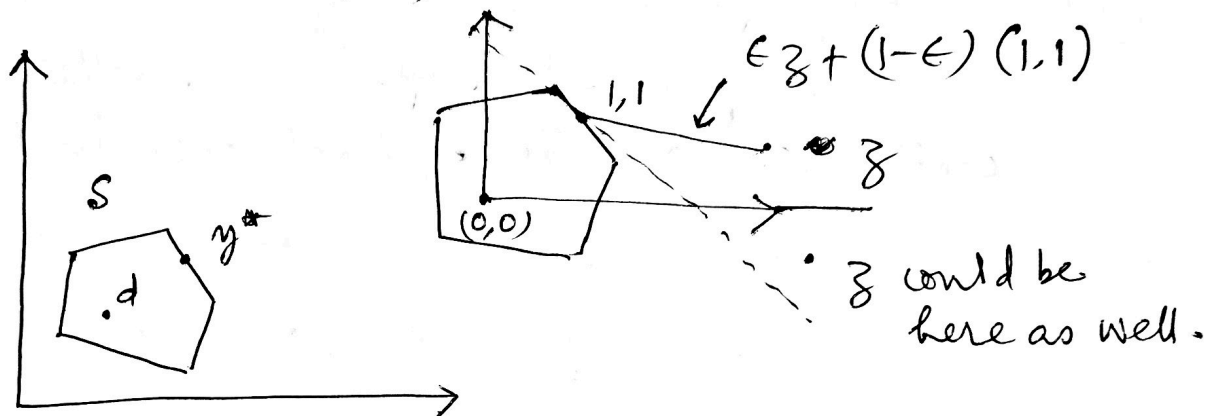
$$L(y_1^*, y_2^*) = (1, 1)$$

Step 2: $x_1 + x_2 \leq 2 \quad \forall x \in aS + b$.

Suppose not, say \exists some $z \in L$ s.t. $z_1 + z_2 > 2$

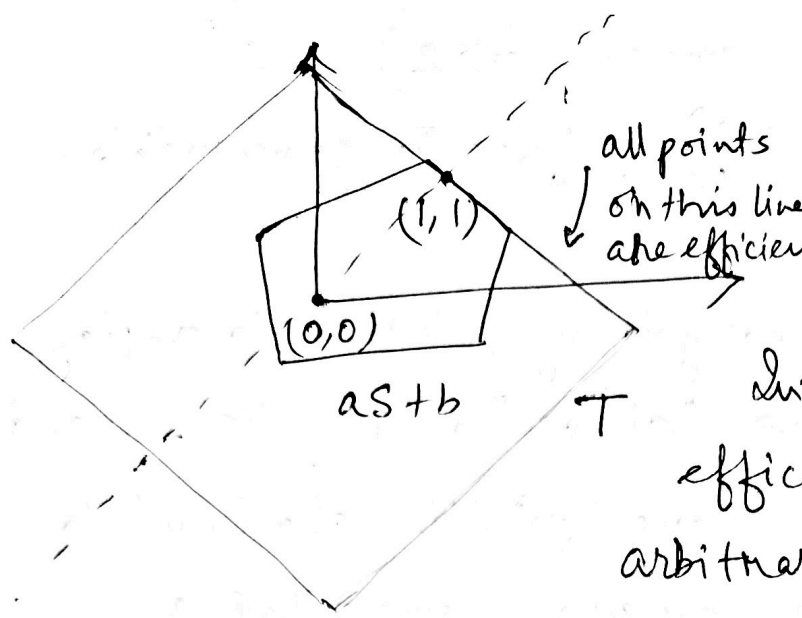
We know if y^* maximizes the Nash product in original domain, $(1,1)$ maximizes the Nash product $y_1 y_2$ in the new domain, L .

Since S was convex, L will also be.



consider a point $(1-\epsilon)(1,1) + \epsilon z = (l_1, l_2)$ for some $\epsilon > 0$ ~~sufficient~~ sufficiently close to 0, the product $l_1 l_2 > 1$. This is a contradiction since $(1,1)$ gives a larger Nash product than the maxima.

Step 3: Enclose $aS + b$ with a square symmetric along ~~the~~ $y_1 = y_2$ line and one side along the $y_1 + y_2 = 2$ line



This is possible since $as+b$ is bounded

Invoke symmetry and efficiency for any arbitrary solution concept ϕ

$$\phi(T, (0,0)) = (1,1)$$

Now, ϕ also satisfies IIA. $as+b \subseteq T$ and contains $(1,1)$, hence $\phi(as+b, (0,0)) = (1,1)$

ϕ satisfies CPAT, apply L^{-1} (possible since all a_i 's are positive)

This gives $\phi(s, d) = y^*$
 $= N(s, d)$

$$\begin{cases} L(s, d) = as+b \\ L(y^*) = (1,1) \end{cases}$$

□